

# Perspective transform

perspective (FOV, aspect, near, far) :  $M$

let  $A = [A_x \ A_y \ A_z \ 1]$  as position input (a-position)

$P = [P_x \ P_y \ P_z \ P_w]$  as position output (gl-Position)

$$P' = [P'_x \ P'_y \ P'_z] = \left[ \frac{P_x}{P_w} \frac{P_y}{P_w} \frac{P_z}{P_w} \right]$$

$P_w = A_z \cdot (-1)$  because  $A_{1z}$  is  $\gg -Z$

$$\text{for } P_y = M_y \cdot A_y, \text{ sic } M_y$$

we know  $P'_y = 1 = \frac{P_y}{P_w} = \frac{M_y \cdot A_{1y}}{P_w} = \frac{M_y \cdot A_{1y}}{-A_{1z}} = \frac{M_y \cdot (-A_{1z} \cdot \tan(\frac{\text{FOV}}{2}))}{-A_{1z}} = \frac{M_y \cdot (-A_{1z} \cdot \tan(\frac{\text{FOV}}{2}))}{-A_{1z}}$

$$\Rightarrow M_y = \frac{1}{\tan(\frac{\text{FOV}}{2})} = \tan(\frac{\pi}{2} - \frac{\text{FOV}}{2})$$

$$\Rightarrow P_y = A_y \cdot \tan(\frac{\pi}{2} - \frac{\text{FOV}}{2})$$

$$\text{for } P_x = M_x \cdot A_x, \text{ sic } M_x$$

we know  $P'_x = 1 = \frac{P_x}{P_w} = \frac{M_x \cdot A_{1x}}{P_w} = \frac{M_x \cdot A_{1x}}{-A_{1z}} = \frac{M_x \cdot A_{1x} \cdot \text{aspect}}{-A_{1z}} = \frac{M_x \cdot (-A_{2z}) \cdot \tan(\frac{\text{FOV}}{2}) \cdot \text{aspect}}{-A_{1z}}$

$$\Rightarrow M_x = \frac{1}{\tan(\frac{\text{FOV}}{2}) \cdot \text{aspect}} = \frac{\tan(\frac{\pi}{2} - \frac{\text{FOV}}{2})}{\text{aspect}}$$

$$\Rightarrow P_x = A_x \frac{\tan(\frac{\pi}{2} - \frac{\text{FOV}}{2})}{\text{aspect}}$$

$$\text{for } P_z = M_z \cdot A_z + M_{zt}, \text{ sic } M_z \ M_{zt}$$

we know  $\begin{cases} P'_{1z} = -1 = \frac{P_z}{P_w} = \frac{M_z A_{1z} + M_{zt}}{A_{1z}} \\ P'_{2z} = 1 = \frac{P_z}{P_w} = \frac{M_z A_{2z} + M_{zt}}{A_{2z}} \end{cases}$

$$\Rightarrow \begin{cases} -\text{near} = -\text{near } M_z + M_{zt} \\ \text{far} = -\text{far } M_z + M_{zt} \end{cases} \Rightarrow \begin{cases} -\text{near } \text{far} = -\text{near } M_z \cdot \text{far} + M_{zt} \cdot \text{far} \\ \text{near } \text{far} = -\text{near } M_z \cdot \text{near} + M_{zt} \cdot \text{near} \end{cases}$$

$$2\text{near } \text{far} = (\text{near } - \text{far}) \cdot M_{zt}$$

$$\Rightarrow P_z = \frac{\text{near } \text{far}}{\text{near } - \text{far}} \cdot A_z + \frac{2\text{near } \text{far}}{\text{near } - \text{far}} \quad \text{https://www.desmos.com/calculator/dhsp5bfzg}$$

$$\text{let } f = \tan(\frac{\pi}{2} - \frac{\text{FOV}}{2})$$

$$\text{rangeInv} = \frac{1}{\text{near } - \text{far}}$$

$$\Rightarrow M = \begin{bmatrix} f & 0 & 0 & 0 \\ 0 & f & 0 & 0 \\ 0 & 0 & \text{rangeInv} \cdot (\text{near} + \text{far}) & -1 \\ 0 & 0 & \text{rangeInv} \cdot (2 \cdot \text{near} \cdot \text{far}) & 0 \end{bmatrix}$$

