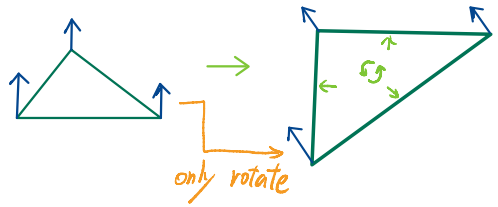
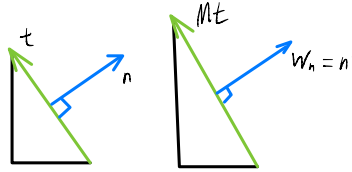


Transforming normals



① 古典幾何: [https://en.wikipedia.org/wiki/Normal_\(geometry\)#Transforming_normals](https://en.wikipedia.org/wiki/Normal_(geometry)#Transforming_normals)

$$\begin{aligned} (W_n) \cdot (Mt) &= 0 \\ \Rightarrow (W_n)^T (Mt) &= 0 \\ \Rightarrow (n^T W^T) (Mt) &= 0 \\ \Rightarrow n^T (W^T M t) &= 0 \\ \Rightarrow n^T (W^T M) t &= 0 \end{aligned}$$



$$\begin{aligned} \text{If } W^T M = I &\Rightarrow n^T t = 0 = n \cdot t = 0 \\ &\Rightarrow W^T = M^{-1} \Rightarrow W = (M^{-1})^T \end{aligned}$$

不過因為用" \cdot "來算, 所以 scale 就無效了,

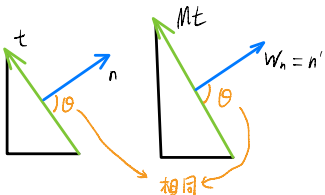
②

<https://paroj.github.io/gltut/Illumination/Tut09%20Normal%20Transformation.html>

$$R \text{ is pure-rotation} \Rightarrow R = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}$$

$$\begin{aligned} R^T &= \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix}, & R^T R &= \begin{bmatrix} (\cos\theta)^2 + (\sin\theta)^2 & -\cos\theta\sin\theta + \sin\theta\cos\theta \\ -\sin\theta\cos\theta + \cos\theta\sin\theta & (\sin\theta)^2 + (\cos\theta)^2 \end{bmatrix} \\ & & &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I \Rightarrow R^T = R^{-1} \end{aligned}$$

$$\text{When } S \text{ is pure scale } a \text{ times} \Rightarrow S = \begin{bmatrix} a & 0 \\ 0 & a \end{bmatrix}, S^T = \begin{bmatrix} a & 0 \\ 0 & a \end{bmatrix} = S$$



$$\text{for } 3 \times 3 \quad M = \underbrace{R_1}_{\text{pure-rotation}} \underbrace{S}_{\text{scale}} \underbrace{R_2}_{\text{pure-rotation}}$$

$$\begin{aligned} (A^T)^T &= (A^{-1})^T \\ (AB)^T &= B^T A^T \\ (AB)^T &= B^T A^T \end{aligned}$$

$$\begin{aligned} W &= R_1 S^{-1} R_2 = (R_1^T)^T (S^T)^T (R_2^T)^T = (R_1^T)^T (S^T)^T (R_2^T)^T \\ &= (R_2^T S^{-1} R_1^T)^T = ((R_2 S R_1)^T)^T = (M^{-1})^T \end{aligned}$$

we will normalize this anyway (in fragment shader) this is a "dot const"